

1.1  $\vec{u} = \vec{a}_1 + 2\vec{a}_2 + 3\vec{a}_3$   
 $\vec{v} = \vec{b}_1 + \vec{c}_2 + \vec{d}_3$   
 $\vec{w} = \vec{d}_1 + 2\vec{d}_2 + q_3 \vec{d}_3$

A	$\vec{u}$	$\vec{v}$	$\vec{w}$
$q_1$	N	Y	Y
$q_2$	N	Y	Y
$q_3$	N	<del>Y</del>	Y

B	$\vec{u}$	$\vec{v}$	$\vec{w}$
$q_1$	Y	N	N
$q_2$	N	Y	Y
$q_3$	N	N	Y

C	$\vec{u}$	$\vec{v}$	$\vec{w}$
$q_1$	Y	N	N
$q_2$	Y	Y	N
$q_3$	N	N	Y

D	$\vec{u}$	$\vec{v}$	$\vec{w}$
$q_1$	Y	N	N
$q_2$	Y	Y	N
$q_3$	Y	Y	Y

$\left| \frac{\partial \vec{v}}{\partial q_1} \right| = 0$   
 $\frac{\partial \vec{v}}{\partial q_2} = c q_2 \vec{c}_1 + s q_2 \vec{c}_3 + \vec{c}_2 + \vec{c}_3$

$\frac{\partial \vec{v}}{\partial q_2} = -s q_2 \vec{c}_1 + c q_2 \vec{c}_3$   
 $\left| \frac{\partial \vec{v}}{\partial q_2} \right| = s q_2^2 + c q_2^2 = 1$

$\left| \frac{\partial \vec{v}}{\partial q_3} \right| = 0$  Notice that  $\vec{v}$  is not dependent on  $q_3$ .

Note:  $D \vec{v} =$

$\left| \frac{D \vec{v}}{\partial q_1} \right|$

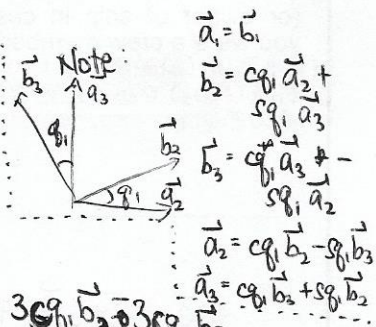
1.2  $\vec{v}$  function of  $t = \vec{v}$  function of  $\vec{q}_1$   
 This is the case at reference A.

1.3  $\vec{v}$  func of  $t \Rightarrow \vec{v}$  func of  $\vec{q}_2$   
 This is the case at reference A B C D

$\left| \frac{D \vec{v}}{\partial q_1} \right| = 0$   $D \vec{v}$  is not dependent on  $q_1$

1.4  $\vec{v} = v_1 \vec{a}_1 + v_2 \vec{a}_2 + v_3 \vec{a}_3$   
 $v_1 = \frac{[\vec{v} \ \vec{a}_2 \ \vec{a}_3]}{[\vec{a}_1 \ \vec{a}_2 \ \vec{a}_3]} = \frac{\vec{v} \cdot \vec{a}_2 \times \vec{a}_3}{\vec{a}_1 \cdot \vec{a}_2 \times \vec{a}_3}$   
 since  $\vec{a}_1$  and  $\vec{a}_2$  and  $\vec{a}_3$  are non coplanar  
 $\vec{a}_2 \times \vec{a}_3 = \vec{a}_1$  which gives us  
 $v_1 = \frac{\vec{v} \cdot \vec{a}_1}{\vec{a}_1 \cdot \vec{a}_1}$  which is by definition  $v_1$ .

1.6  $\vec{u} = \vec{a}_1 + 2\vec{a}_2 + 3\vec{a}_3$   
 $\vec{u} = \vec{b}_1 + 2c q_1 \vec{b}_2 + 2s q_1 \vec{b}_2 + 3c q_1 \vec{b}_3 + 3s q_1 \vec{b}_3$   
 $\frac{\partial \vec{u}}{\partial q_1} = -2s q_1 \vec{b}_2 + 2c q_1 \vec{b}_3 + 3c q_1 \vec{b}_2 + 3s q_1 \vec{b}_3$   
 convert  $\vec{b}_2$  and  $\vec{b}_3$  to  $\vec{a}_1, \vec{a}_2, \vec{a}_3$   
 $= -2s q_1 c q_1 \vec{a}_2 - 2s q_1 s q_1 \vec{a}_3 - 2c q_1 c q_1 \vec{a}_3 + 2c q_1 s q_1 \vec{a}_2 - 3s q_1 c q_1 \vec{a}_3 + 3s q_1 s q_1 \vec{a}_2 + 3c q_1 c q_1 \vec{a}_2 + 3c q_1 s q_1 \vec{a}_3$   
 $= -2\vec{a}_3 + 3\vec{a}_2$



1.5  $A \left| \frac{\partial \vec{v}}{\partial q_1} \right|$

- (a) 0, 3, -2
- (b) 0,  $-2s q_1 + 3c q_1$ ,  $-2c q_1 - 3s q_1$
- (c) 0, 0, 0 bec  $\vec{u}$  is not dependent on  $q_1$

1.7

Note:

$$\vec{a}_1 = \dot{\theta} \vec{b}_1 - s\theta \vec{b}_2$$

$$\vec{a}_2 = s\theta \vec{b}_1 + c\theta \vec{b}_2$$

$$A \vec{v} = f \vec{a}_1 + g \vec{a}_2$$

$$B \vec{v} = f (c\theta \vec{b}_1 - s\theta \vec{b}_2) + g (s\theta \vec{b}_1 + c\theta \vec{b}_2)$$

$$\frac{\partial \vec{v}}{\partial q_2} = \frac{\partial f}{\partial q_2} (c\theta \vec{b}_1 - s\theta \vec{b}_2) + f (-s\theta \vec{b}_1 - c\theta \vec{b}_2) \frac{\partial \theta}{\partial q_2}$$

$$+ \frac{\partial g}{\partial q_2} (s\theta \vec{b}_1 + c\theta \vec{b}_2) + g (c\theta \vec{b}_1 - s\theta \vec{b}_2) \frac{\partial \theta}{\partial q_2}$$

$$\frac{\partial}{\partial q_1} \left( \frac{\partial \vec{v}}{\partial q_2} \right) = \frac{\partial}{\partial q_1} \left( \frac{\partial f}{\partial q_2} \vec{a}_1 + f \vec{a}_2 \frac{\partial \theta}{\partial q_2} + \frac{\partial g}{\partial q_2} \vec{a}_2 + g \vec{a}_1 \frac{\partial \theta}{\partial q_2} \right)$$

$$= \frac{\partial^2 f}{\partial q_1 \partial q_2} \vec{a}_1 - \frac{\partial f}{\partial q_1} \frac{\partial \theta}{\partial q_2} \vec{a}_2 - f \frac{\partial^2 \theta}{\partial q_1 \partial q_2} \vec{a}_2$$

$$+ \frac{\partial^2 g}{\partial q_1 \partial q_2} \vec{a}_2 + \frac{\partial g}{\partial q_1} \frac{\partial \theta}{\partial q_2} \vec{a}_1 + g \frac{\partial^2 \theta}{\partial q_1 \partial q_2} \vec{a}_1$$

$$\frac{\partial \vec{v}}{\partial q_1} = \frac{\partial f}{\partial q_1} \vec{a}_1 + \frac{\partial g}{\partial q_1} \vec{a}_2$$

$$\frac{\partial}{\partial q_2} \left( \frac{\partial \vec{v}}{\partial q_1} \right) = \frac{\partial^2 f}{\partial q_1 \partial q_2} \vec{a}_1 + \frac{\partial f}{\partial q_1} \frac{\partial \theta}{\partial q_2} (-\vec{a}_2)$$

$$+ \frac{\partial^2 g}{\partial q_1 \partial q_2} \vec{a}_2 + \frac{\partial g}{\partial q_1} \frac{\partial \theta}{\partial q_2} (\vec{a}_1)$$

$$\frac{\partial}{\partial q_1} \left( \frac{\partial \vec{v}}{\partial q_2} \right) - \frac{\partial}{\partial q_2} \left( \frac{\partial \vec{v}}{\partial q_1} \right) = -f \frac{\partial^2 \theta}{\partial q_1 \partial q_2} \vec{a}_2 + g \frac{\partial^2 \theta}{\partial q_1 \partial q_2} \vec{a}_1$$

$$= (g \vec{a}_1 - f \vec{a}_2) \frac{\partial^2 \theta}{\partial q_1 \partial q_2}$$

1.8 (a)  $\vec{v} \cdot \frac{d\vec{v}}{dt} = \sum v_i \vec{a}_i \cdot \sum \frac{dv_i}{dt} \vec{a}_i$

$$= \sum v_i \frac{dv_i}{dt}$$

(b)  $|\vec{v}| \frac{d|\vec{v}|}{dt} = \left( \sqrt{\sum v_i^2} \right) \left( \frac{1}{2} \sum v_i^2 \right)^{-1/2} \left( \sum v_i \frac{dv_i}{dt} \right)$

$$= \sum v_i \frac{dv_i}{dt}$$

since (a) = (b), we just showed  $\vec{v} \cdot \frac{d\vec{v}}{dt} = |\vec{v}| \frac{d|\vec{v}|}{dt}$

$$|\vec{v}| \frac{d|\vec{v}|}{dt} = \vec{v} \cdot \frac{d\vec{v}}{dt}$$

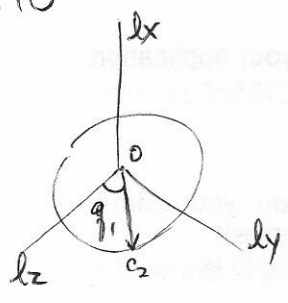
$$\vec{u} = \frac{\vec{v}}{|\vec{v}|} \rightarrow -\frac{1}{2} \left( \sum v_i^2 \right)^{-3/2} \left( \sum v_i \frac{dv_i}{dt} \right)$$

$$= -|\vec{v}|^{-3} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$\frac{d\vec{u}}{dt} = \frac{d\vec{v}}{dt} |\vec{v}|^{-1} + \frac{d|\vec{v}|}{dt} \vec{v}^{-1}$$

$$= \frac{d\vec{v}}{dt} |\vec{v}|^{-1} - |\vec{v}|^{-3} \vec{v} \cdot \frac{d\vec{v}}{dt} \vec{v}$$

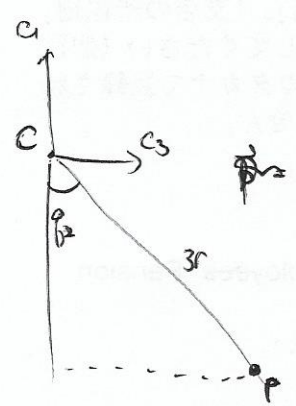




$$\begin{aligned} \vec{c}_1 &= \vec{l}_x \\ \vec{c}_2 &= -c q_1 \vec{l}_z + s q_1 \vec{l}_y \\ \vec{c}_3 &= s q_1 \vec{l}_z + c q_1 \vec{l}_y \\ \vec{v}_{oc} &= r \vec{c}_2 \end{aligned}$$

$$\frac{\partial \vec{c}_2}{\partial q_1} = s q_1 \vec{l}_z + c q_1 \vec{l}_y = \vec{c}_3$$

$$\frac{\partial \vec{c}_3}{\partial q_1} = c q_1 \vec{l}_z - s q_1 \vec{l}_y = -\vec{c}_2$$



$$\begin{aligned} \vec{v}_{EP} &= 3r(-c q_2 \vec{c}_1 + s q_2 \vec{c}_3) \\ \vec{p} &= \vec{v}_{oc} + \vec{v}_{EP} \\ \vec{p} &= -3r c q_2 \vec{c}_1 + r \vec{c}_2 + 3r s q_2 \vec{c}_3 \end{aligned}$$

Note:

$$\frac{\partial \vec{c}_1}{\partial t} = 0 \quad \frac{\partial \vec{c}_2}{\partial t} = \frac{\partial \vec{c}_2}{\partial q_1} \dot{q}_1 = \vec{c}_3 \dot{q}_1$$

$$\frac{\partial \vec{c}_3}{\partial t} = \frac{\partial \vec{c}_3}{\partial q_1} \dot{q}_1 = -\vec{c}_2 \dot{q}_1$$

$$\begin{aligned} \frac{\partial \vec{p}}{\partial t} &= r \left[ 3s q_2 \dot{q}_2 \vec{c}_1 - \cancel{0} + 3c q_2 \dot{q}_2 \vec{c}_3 - 3s q_2 \dot{q}_1 \vec{c}_2 + \dot{q}_1 \vec{c}_3 \right] \\ &= r \left[ \dot{q}_1 (\vec{c}_3 - 3s q_2 \vec{c}_2) + 3\dot{q}_2 (s q_2 \vec{c}_1 + c q_2 \vec{c}_3) \right] \end{aligned}$$

$$\begin{aligned} 1.11 \quad \vec{u} &= \frac{\vec{v}}{|\vec{v}|} \\ \frac{d\vec{u}}{dt} &= \frac{d\vec{v}}{dt} |\vec{v}|^{-1} + \vec{v} \frac{d|\vec{v}|^{-1}}{dt} \\ \frac{d^2\vec{u}}{dt^2} &= \frac{d^2\vec{v}}{dt^2} |\vec{v}|^{-1} + 2 \frac{d\vec{v}}{dt} \frac{d|\vec{v}|^{-1}}{dt} + \vec{v} \frac{d^2|\vec{v}|^{-1}}{dt^2} \end{aligned}$$

Note:

$$\begin{aligned} \frac{d|\vec{v}|^{-1}}{dt} &= -\frac{1}{2} (\sum v_i^2)^{-3/2} \sum 2v_i \frac{dv_i}{dt} \\ &= -|\vec{v}|^{-3} \underbrace{\vec{v} \cdot \frac{d\vec{v}}{dt}}_0 \\ &= 0 \end{aligned}$$

$$\begin{aligned} \frac{d^2|\vec{v}|^{-1}}{dt^2} &= \frac{d-|\vec{v}|^{-3}}{dt} \cdot \vec{v} \cdot \frac{d\vec{v}}{dt} + (-|\vec{v}|^{-3}) \frac{d(\vec{v} \cdot \frac{d\vec{v}}{dt})}{dt} \\ &= -(-3/2) (\sum v_i^2)^{-5/2} \sum 2v_i \frac{dv_i}{dt} \sum v_i \frac{dv_i}{dt} \\ &\quad - |\vec{v}|^{-3} \left( \sum \frac{dv_i}{dt} \frac{dv_i}{dt} + \sum v_i \frac{d^2v_i}{dt^2} \right) \\ &= -3|\vec{v}|^{-5} \underbrace{\left( \vec{v} \cdot \frac{d\vec{v}}{dt} \right)^2}_0 - |\vec{v}|^{-3} \underbrace{\left( \frac{d\vec{v}}{dt} \cdot \frac{d\vec{v}}{dt} + \vec{v} \cdot \frac{d^2\vec{v}}{dt^2} \right)}_0 \\ &= 1 \end{aligned}$$

$$\frac{d^2\vec{u}}{dt^2} = \vec{n}_3 * 1 + 2 \vec{n}_2 * 0 + \vec{n}_1 * 1 = \vec{n}_3 + \vec{n}_1$$

$$\boxed{\left| \frac{d^2\vec{u}}{dt^2} \right| = \sqrt{2}}$$